

Lecture 2 : The curse of dimensionality ; Neural Networks and approximation.

[Bach '21] [Telgarski, '20]
(DLT 'Fall 20).

Basic Supervised Learning Setup

Goal. Given data $\{(x_i, y_i)\}_{i=1..n}$ with $x_i \in \mathcal{X}$ (high-dimension)
 $y_i \in \mathcal{Y}$ labels.
 \downarrow input label.

estimate a mapping $f: \mathcal{X} \rightarrow \mathcal{Y}$ that

? generalises to ? unseen data
 \uparrow
glorified Interpretation

→ IID Assumption : data is drawn iid from a distribution μ on $\mathcal{X} \times \mathcal{Y}$.

→ Point-wise loss $l: \mathcal{Y} \times \mathcal{Y} \rightarrow \mathbb{R}$

eg: $l(y, y') = \log(1 + \exp(-yy'))$

$l(y, y') = \frac{1}{2} |y - y'|^2$

$\hookrightarrow \mathcal{Y} = \mathbb{R}$

Given any $f: \mathcal{X} \rightarrow \mathcal{Y}$, this defines

population risk $R(f) = \mathbb{E}_{\mu} [l(f(x), y)]$

($\mathbb{E} \hat{R}(f) = R(f)$)

empirical risk $\hat{R}(f) = \frac{1}{n} \sum_{i=1}^n l(f(x_i), y_i) \leftarrow$ unbiased estimator of R .

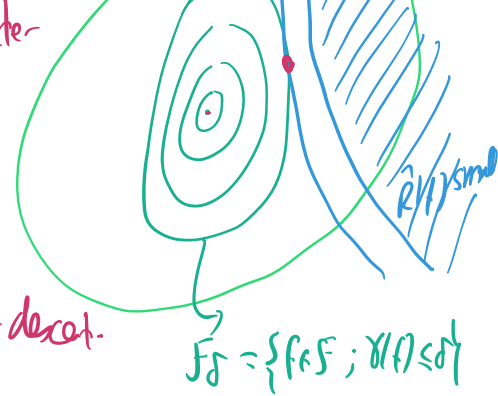
→ Hypothesis space $\mathcal{F} = \{f: \mathcal{X} \rightarrow \mathcal{Y}\}$

Assume that \mathcal{F} comes with a norm : we can assign to each $f \in \mathcal{F}$ a complexity measure $\gamma(f)$

Example : \rightarrow norms over the NN parameter weights.

\rightarrow number of neurons

\rightarrow number of gradient-steps for models f using gradient-descent.



\rightarrow Empirical Risk Minimization (ERM).

we search for small empirical risk using small complexity.

\hookrightarrow (C) $\min_{\text{constrained } ||f|| \leq \delta} \hat{R}(f)$ (P) $\min_{\text{penalize } f \in F} \hat{R}(f) + \lambda \cdot ||f||$
 \hookrightarrow Lagrange Multiplier.

(I) $\min_{\text{interpret.}} ||f||$ s.t. $\hat{R}(f) = 0$ (situations with no noise) $f(x_i) = y_i \quad i=1 \dots n$

\rightarrow Basic decomposition of error / risk

Let $\hat{f} \in F_S$ produced by an arbitrary algorithm \rightarrow (only sees \hat{R})

Then

$$\begin{aligned}
 R(\hat{f}) - \inf_{f \in F} R(f) &= R(\hat{f}) - \inf_{f \in F_S} R(f) + \inf_{f \in F_S} R(f) - \inf_{f \in F} R(f) \\
 &= \underbrace{R(\hat{f}) - \hat{R}(\hat{f})}_{\text{approximation error}} + \underbrace{\hat{R}(\hat{f}) - \inf_{f \in F_S} \hat{R}(f)}_{\text{optimization error}} + \underbrace{\inf_{f \in F_S} \hat{R}(f) - \inf_{f \in F_S} R(f)}_{\text{generalization error}} \\
 &\leq 2 \sup_{f \in F_S} |\hat{R}(f) - R(f)| + \epsilon_{\text{appr}} + \epsilon_{\text{opt}}.
 \end{aligned}$$

↳ statistical error.

3 sources of error $\rightarrow \epsilon_{\text{appr}}$ in regression $R(f) = \|f - f^*\|_2^2$
 $\{ (x_i, y_i) \}$, with $y_i = f^*(x_i)$
 $\inf_{f \in \mathcal{F}} \|f - f^*\|_2^2$
 \rightarrow As \mathcal{F} increases, ϵ_{appr} decreases.

\rightarrow Statistical error $\left(\sup_{f \in \mathcal{F}_\sigma} |R(f) - \hat{R}(f)| \right) \leftarrow$ a random quantity.

measures uniform fluctuations over the ball \mathcal{F}_σ .

Two main quantities drive this error: $\begin{cases} n : \text{the number of datapoints} \\ \sigma : \text{size of } \mathcal{F}_\sigma \text{ ball.} \end{cases}$

What is the expected behavior?

Fix f first.

(x_i, y_i) iid.

$$\hat{R}(f) - R(f) = \frac{1}{n} \sum_{i=1}^n [\ell(f(x_i), y_i) - \mathbb{E} \ell(f(x), y)]$$

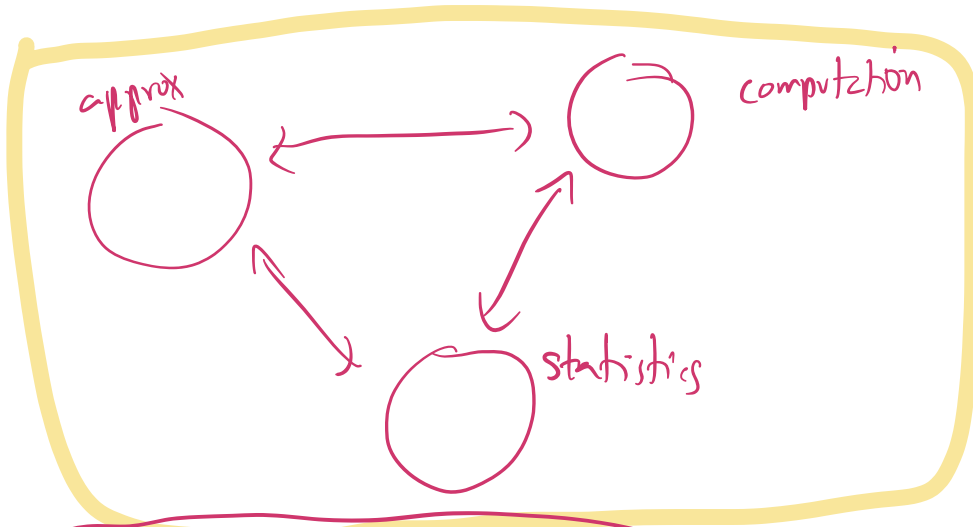
$$\Rightarrow |\hat{R}(f) - R(f)| \sim \frac{\text{std}(\ell(f(x), y))}{\sqrt{n}} \quad \begin{matrix} \text{(non-asymptotic in } n) \\ \text{(quantified in high-prob using Chernoff tail bounds)} \end{matrix}$$

↳ From point-wise control to uniform control, requires some tools from concentration / empirical processes (Rademacher averages, etc)

$$\epsilon_{\text{stat}} \sim \frac{h(\sigma, \mathcal{F})}{\sqrt{n}} \leftarrow \text{need to fight each other!}$$

↳ Optim error $\hat{R}(\hat{f}) - \inf_{f \in \mathcal{F}} \hat{R}(f)$ measures our ability to solve ERM.

↳ f^* is non-convex in most practical situations!



The curse of dimensionality 'How do approximation and statistical errors behave as input dimension grows?

statistics: we observe $\{(x_i, f^*(x_i))\}_{i=1 \dots n}$ $x_i \sim \mathcal{N}(0, I_d)$
 f^* unknown. $x_i \in \mathbb{R}^d$.

Q: How many samples are needed to estimate f^* up to accuracy ε , i.e. $\mathbb{E}_x |\hat{f}(x) - f^*(x)|^2 \leq \varepsilon$?
 (sample complexity).

↳ suppose first f^* is linear: $f^*(x) = \langle x, \theta^* \rangle$ $\theta^* \in \mathbb{R}^d$.

$$\mathcal{F} = \left\{ f: \mathbb{R}^d \rightarrow \mathbb{R}; f(x) = \langle x, \underset{\uparrow}{\theta} \rangle \right\} \cong \mathbb{R}^d$$

A: $n = d$ are sufficient for exact recovery (and necessary!)
 (solve a linear system $\langle x_i, \theta \rangle = \langle x_i, \theta^* \rangle$ $i=1 \dots d$).

Remark: $f^*(x) = \varphi(\langle x, \theta^* \rangle)$ φ is even function, smooth.

A: $n = d+1$ sample are sufficient and also necessary $\varphi(t) = |t| = \cos t$.

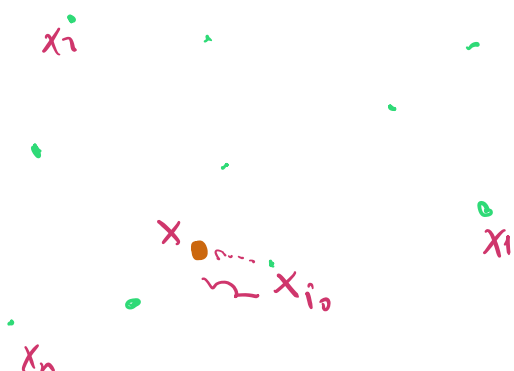
[57B'21]

↳ Suppose now that f^* is only locally linear, i.e.

(β) Lipschitz: $|f(x) - f(x')| \leq \beta \cdot \|x - x'\|_2 \leftarrow$

$\mathcal{F} = \{ f: \mathbb{R}^d \rightarrow \mathbb{R} ; f \text{ bounded, Lipschitz} \}$: a Banach space, with norm

$\|f\|_{\mathcal{F}} = \|f\|_{\infty} + \text{Lip}(f).$



We consider the smoothest interpolant:

$\hat{f} = \underset{\mathcal{F}}{\text{argmin}} \{ \text{Lip}(f) ; f(x_i) = f^*(x_i) \}$
 [ERM in interpolant form]

For any x ,

$$\begin{aligned} |\hat{f}(x) - f^*(x)| &\leq |\hat{f}(x) - \hat{f}(x_{i_0})| + |\hat{f}(x_{i_0}) - f^*(x_{i_0})| \\ &\quad + |f^*(x_{i_0}) - f^*(x)| \\ &\leq \beta \|x - x_{i_0}\| + 0 \\ &\leq 2\beta \|x - x_{i_0}\| \end{aligned}$$

$\Rightarrow \mathbb{E}_{x \sim \underbrace{N(0, I_d)}_{\mu}} |\hat{f}(x) - f^*(x)|^2 \leq 4\beta^2 \underbrace{\mathbb{E}_{x, x_{i_0}} \|x - x_{i_0}\|^2}_{\sim W_2^2(\mu, \hat{\mu}_n)} \sim n^{-1/d}$
 training set $\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n x_i$ [Dudley '68]

As a consequence, if $\varepsilon \sim n^{-1/d}$ [BLG '14].

$\Rightarrow n \sim \varepsilon^{-d}$ we can ensure that we learn with accuracy ε . \rightarrow cursed by dimension

↳ Is this sample complexity also necessary?

• Consider the box $B = [-1/2, 1/2]^d$



and the function $\psi: B \rightarrow \mathbb{R}$

$$\psi(x) = \text{dist}(x; \partial B)$$

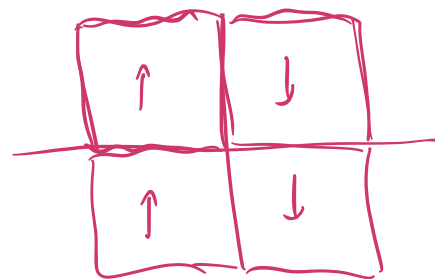
Exercise: ψ is 1-Lipschitz.

• Consider for each $z \in \{-1/2, 1/2\}^d$
an arbitrary sign $g(z) = \pm 1$

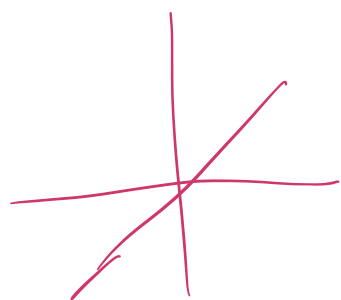


$$f^*(x) = \sum_{z \in \mathbb{Z}^d} g(z) \psi(x-z)$$

f^* is 1-Lipschitz and supported
in $[-1, 1]^d$.



→ Claim: if $n \ll 2^d$, then any estimator will
incur in a relative error



$$\frac{\mathbb{E}_x |\hat{f}(x) - f^*(x)|^2}{\mathbb{E}_x |f^*(x)|^2} = \Theta(1)$$

↳ To summarise:

→ linear functions (or generalised linear functions)

$n \sim d$ (easy)

→ Lipschitz functions

→ $n \sim \varepsilon^{-d}$

(impossible)

In between, Sobolev class:

$$W(s) = \left\{ f: \mathbb{R}^d \rightarrow \mathbb{R} ; f \text{ has } s\text{-derivatives bounded in } L_p \right\}$$

sample complexity $n \sim \varepsilon^{-\frac{d+2s}{s}}$ [Tsybakov].

$$\tilde{d} = d/s \quad \sim \varepsilon^{-\tilde{d}}$$

→ unless $s = \Theta(d)$, no real change.

Conclusion: we will need to search for alternatives.

Shallow Neural Networks and Approximation

→ Consider $\sigma: \mathbb{R} \rightarrow \mathbb{R}$ (Lipschitz) activation function

$$f_K(x; \theta) = \sum_{k=1}^K \underbrace{c_k \sigma(\langle x, a_k \rangle + b_k)}_{\text{ridge function}} \quad \begin{array}{l} x \in \mathbb{R}^d \\ a_k \in \mathbb{R}^d \\ b_k, c_k \in \mathbb{R} \end{array}$$

$$\theta = \{ a_k, b_k, c_k \}_{k=1}^K.$$

→ Space of functions represented with shallow NNs is $H_\sigma = \{ f_K(\cdot; \theta) ; \theta ; K \in \mathbb{N} \}$

Q: How expressive is this set?

Universal Approximation

For a given metric d defined over continuous functions,
 $\forall f \in C(\mathbb{R}^d)$ and $\forall \varepsilon > 0$, there exist $\hat{f} \in H_\sigma$

such that $d(f, g) \leq \varepsilon$.

→ To get intuition, let us first consider a 3-layer approximation.

Theorem Let $g: \mathbb{R}^d \rightarrow \mathbb{R}$ continuous, $\varepsilon > 0$, $\Omega = [0, 1]^d$,
and let $\delta > 0$ so that $\|x - x'\|_\infty < \delta$, $x, x' \in \Omega$,
then $|g(x) - g(x')| \leq \varepsilon$. Then there exists a 3-layer
Relu network f with $\mathcal{O}(\delta^{-d})$ and $\|f - g\|_1 \leq \varepsilon$.
 $(L^1(\Omega))$

Proof: [Telgarski '20]

Lemma: let $U \subseteq \mathbb{R}^d$, with a partition \mathcal{P} of U
into rectangles; $\mathcal{P} = (R_1 \dots R_N)$, each with lengths
 $\leq \delta$. Then \exists scalars $\alpha_1 \dots \alpha_N$ with

$$|\mathcal{P}| \sim \delta^{-d} \sup_{x \in U} |g(x) - h(x)| \leq \varepsilon, \text{ with } h(x) = \sum_i \alpha_i \mathbb{1}_{[R_i]}$$

In other words, piece-wise constant approximation has
small error provided pieces are sufficiently small.

let \mathcal{P} the partition from above of $U = [0, 1+c]^d$
into rectangles $R_i: \prod_j [a_j, b_j)$ with $b_j - a_j \leq \delta$.

$$h(x) = \sum_i \alpha_i \mathbb{1}_{R_i}, \text{ so } \|g - h\|_1 \leq \varepsilon.$$

We construct a network of the form

$$f(x) = \sum \alpha_i g_i(x) \text{ where each } g_i \text{ is}$$

a ReLU net that approximates $\mathbb{1}_{R_i}$.

$$\|f - g\|_1 \leq \overbrace{\|f - h\|_1} + \overbrace{\|h - g\|_1} \leq \varepsilon \text{ from Lemma.}$$

$$= \left\| \sum_i \alpha_i (\mathbb{1}_{R_i} - g_i) \right\|_1 + \varepsilon$$

$$\leq \sum_i |\alpha_i| \|\mathbb{1}_{R_i} - g_i\|_1 + \varepsilon \leq 2\varepsilon$$

If we can build g_i so that

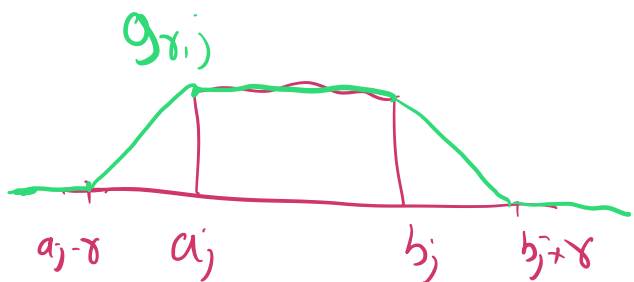
$$\rightarrow \|\mathbb{1}_{R_i} - g_i\|_1 \leq \frac{\varepsilon}{\sum_i |\alpha_i|}, \text{ then we are done.}$$

• Fix i , $R_i = \otimes [a_j, b_j)$. For $\delta > 0$, and for each coordinate $j \in \{1, \dots, d\}$, let

$$g_{\delta,j}(z) = \sigma\left(\frac{z - (a_j - \delta)}{\delta}\right) - \sigma\left(\frac{z - a_j}{\delta}\right)$$

$$- \sigma\left(\frac{z - b_j}{\delta}\right) + \sigma\left(\frac{z - (b_j + \delta)}{\delta}\right)$$

$$\hookrightarrow \sigma(t) = \max(0, t)$$



$$g_\delta(x) = \sigma\left(\left|\sum_j g_{\delta,j}(x)\right| - (d-1)\right)$$

\hookrightarrow we verify that

$$(i) \quad g_\delta(x) = \begin{cases} 1 & \text{if } x \in R_i \\ 0 & \text{if } x \notin \otimes (a_j - \delta, b_j + \delta) \\ (c.i.) & \text{otherwise.} \end{cases}$$



$$(ii) \|g_\gamma - \Pi_{R_i}\|_1 \leq O(\gamma) \quad \square$$

Remark
Question

Are the two hidden layers necessary?

A: Hell no! Recall a classic result in polynomial approximation

Theorem (Stone-Weierstrass) Let $\Omega = [0, 1]^d$. Let \mathcal{F} be a function class satisfying:

- (i) Each $f \in \mathcal{F}$ is continuous
- (ii) $\forall x \in \Omega, \exists f \in \mathcal{F}$ such that $f(x) \neq 0$.
- (iii) $\forall x \neq x' \in \Omega, \exists f \in \mathcal{F}$ $f(x) \neq f(x')$.
- (iv) \mathcal{F} is an algebra: closed under multiplication and vector space operations.

Then \mathcal{F} enjoys universal approx: any continuous $g: \mathbb{R}^d \rightarrow \mathbb{R}$
 $\forall \varepsilon > 0, \exists \underline{f} \in \mathcal{F}$ with $\sup_x |f(x) - g(x)| \leq \varepsilon$.

↳ This theorem can be used to establish UAT for Ho with general choices of σ :

↳ σ sigmoidal $\lim_{t \rightarrow -\infty} \sigma(t) = 0, \lim_{t \rightarrow +\infty} \sigma(t) = 1$

[Hornik et al 89]

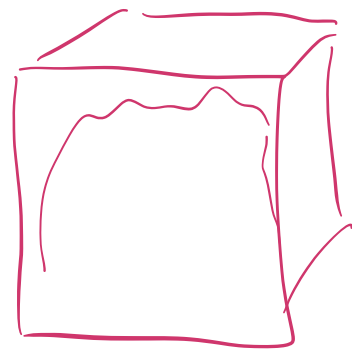
↳ $\sigma \neq$ polynomial (Ueshnov)

↳ Is this surprising?

↳ Are the approximation rates cursed using Ho?

The Fourier perspective

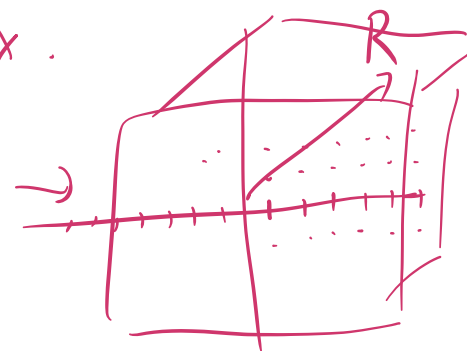
→ let $f \in C(\mathbb{R}^d)$ and consider its restriction to a compact Ω (eg $\Omega = (0,1)^d$).



For $\xi \in \mathbb{Z}^d$, consider its Fourier decomposition

$$\hat{f}(\xi) = \left\langle f, e^{i\langle x, \xi \rangle} \right\rangle_{L^2(\Omega)} =$$

$$= \int_{\Omega} f(x) e^{-i\langle x, \xi \rangle} dx.$$



↳ Fourier Inversion Lemma:

$$f_M(x) = \sum_{\|\xi\| \leq R} \hat{f}(\xi) e^{i\langle x, \xi \rangle}$$

\downarrow
 f in $L^2(\Omega)$ as $M, R \rightarrow \infty$

M is the number of frequencies inside $\{\|\xi\| < R\}$.

$$e^{i\langle x, \xi \rangle} = \sigma(\langle x, \xi \rangle) \text{ with } \sigma(t) = e^{it} = \cos t + i \sin t.$$

f_M is a shallow NN with M periodic neurons.

We have tight control of $\left\{ \begin{array}{l} \text{how regularity of } f \\ \uparrow \\ \text{decay of } \hat{f} \text{ as } \|\xi\| \text{ grows.} \end{array} \right.$

$f \in W^s$
sublev.

$$\Rightarrow \|f - f_M\| = O(M^{-s/d}) \quad \begin{array}{l} \text{[Tsybakov]} \\ \text{[de Vore]} \\ \text{etc.} \end{array}$$

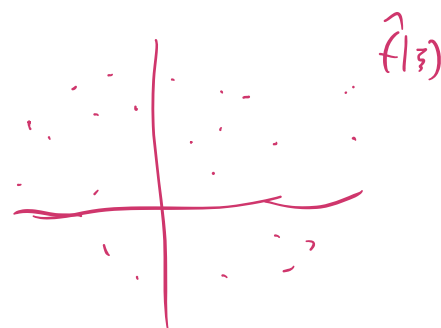
curse of dim in approximation!

↳ Overcome this curse?

Fourier Representation, in L_1

$$\hat{f}(z) = \int f(x) e^{-i\langle x, z \rangle} dx$$

$$f(x) = \int \hat{f}(z) e^{+i\langle x, z \rangle} dz$$



If $\|\hat{f}\|_1$ is finite, $\|\hat{f}\|_1 = \int |\hat{f}(z)| dz < +\infty$.

Idea: $f(x) = \int \sigma(\langle x, w \rangle) g(w) dw$ with g integrable $\|g\|_1 < +\infty$.

$$g(w) = \text{sign}(g(w)) \cdot \|g\|_1 \cdot \underbrace{\left(\frac{|g(w)|}{\|g\|_1} \right)}_{q(w)}$$

$$q \geq 0$$

$$\int q(w) dw = 1$$

$$f(x) = \int \sigma(\langle x, w \rangle) \cdot \text{sign}(g(w)) \cdot \|g\|_1 \cdot q(w) dw$$

$\Rightarrow q$ is a prob. density.

$$= \mathbb{E}_q \left[\underbrace{\sigma(\langle x, w \rangle) \cdot \text{sign}(g(w))}_{\phi(x, w)} \right] \cdot \|g\|_1 \quad |\phi| \leq 1$$

↳ $\hat{f}_M(x) = \frac{1}{M} \sum_{m=1}^M \phi(x, w_m)$, $w_i \sim q$ iid. Monte Carlo estimator

$$\mathbb{E} \|f - \hat{f}_M\|^2 \leq \|g\|_1^2 \frac{\mathbb{E}_q (\mathbb{E}_x \phi(x, w)^2)}{M} \leq \frac{(\|g\|_1^2) \sup_w (\mathbb{E}_x \phi^2)}{M}$$

Curse of dim is avoided, provided $\|g\|_1 < +\infty$.

Theorem: (Barron' 93) Suppose $C = \int \|\widehat{\nabla f(z)}\| dz < +\infty$
with $f, \hat{f} \in L_1$. Then we can approximate f ~~with~~
to accuracy ε with ReLU/Sigmoid units with $\sim \frac{C}{\varepsilon^2}$
(No curse!).

↳ Main q: When/Why is C small.

Conclusions / Take-home:

- (*) Learning in high-dim efficiently requires new function spaces, adapted to the physical world (images, sounds, etc.).